2 – Assist. prof. Dr.Abdulateef Hassan Shoman and Lecturer Dr.Ali Hassan Zayer Some reliable techniques for solving higher-orderVolterra integro-differential equations

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Abstract

 In this paper, the Adomian Decomposition Method (ADM) and Variational Iteration Method (VIM) are applied to solve boundary value problems for higher-order Volterra integro-differential equations. The numerical results obtained with minimum amount of computation are compared with the exact solutions to show the efficiency of the techniques. The results show that the variational iteration method is of high accuracy, more convenient and efficient for solving integro-differential equations.

Keywords: Adomian decomposition method, variational iteration method, integro-differential equation.

2. Introduction In this work, we consider the Volterra integro–differential equation of the second kind as follows:

$$\sum_{j=0}^{k} p_j(x)u^{(j)}(x) = f(x) + \int_a^x K(x,t)G(u(t))dt$$

:with the initial or boundary conditions			
,(r = 0,1,2,,(n − 1	$,u^{(r)}(a) = \alpha_{r}$	(2)
,(r = n,(n + 1),,(k - 1	$,u^{(r)}(b) = \beta_r$	(3)
where $u(i)(\mathbf{x})$ is the i th derivation	ive of the unknown	function u(x) that w	/ /ill

where $u^{(j)}(x)$ is the jth derivative of the unknown function u(x) that will be determined, K(x,t) is the kernel of the equation, $a \le x \le b$, f(x) and $p_j(x)$ are analytic functions, G is analytic function of u, and α_r ; $0 \le r \le (n-1)$ and β_r ; $n \le r \le (k-1)$ are real finite constants.

In recent years there has been a growing interest in the integro-differential equation. The integro-differential equations be an important branch of modern mathematics. It arises frequently in many applied areas which include engineering, electrostatics, mechanics, the theory of elasticity, potential, and mathematical physics [3,4,6,10,27].

Recently, Wazwaz (2001) presented an efficient and numerical procedure for solving boundary value problems for higher–order integro–differential equations. A variety of methods, exact, approximate and purely numerical techniques are available to solve nonlinear integro–differential equations. These methods have been of great interest to several authors and used to solve many nonlinear problems. Some of these techniques are Adomian de–composition method [4,24], modified Adomian decomposition method [30], Variational iteration method [7,32,33] and homotopy perturbation method [30] and many methods for solving integrodifferential equations [2,3,6,16–21,28].

More details about the sources where these equations arise can be found in physics, biology, and engineering applications as well as in advanced integral equations. Some works based on an iterative scheme have been focusing on the development of more advanced and efficient methods for integro–differential equations such as the variational iteration method which is a simple and Adomian decomposition method [8,9,24,31], and the modi– fied decomposition method for solving Volterra–Fredholm integral and inte– gro–differential equations which is a simple and powerful method for solving a wide class of nonlinear problems [24]. The Taylor polynomial solution of integro–differential equations has been studied in [27]. The use of Lagrange interpolation in solving integro–differential equations was investigated by Marzban [26]. The VIM has been successfully applied for solving integral and integro–differential equations [5,24,30].

A variety of powerful methods has been presented, such as the homotopy analysis method [30], homotopy perturbation method [6,30], operational matrix with Block–Pulse functions method [3], variational iteration method [5,30] and the Adomian decomposition method [4,24,30]. Some fundamental works on various aspects of modifications of the Adomian's decomposition method are given by Araghi [1]. The modified form of Laplace decomposition method has been introduced by Manafianheris [25]. Babolian et. al, [3], applied the new direct method to solve nonlinear Volterra–Fredholm integral and integro–differential equation using operational matrix with block–pulse functions. The Laplace transform method with the Adomian decomposition method to establish exact solutions or approximations of the nonlinear Volterra integro–differential equations, Wazwaz [31]. Recently, the authors have used several methods for the numerical or the analytical solutions of linear and nonlinear Volterra and Fredholm integro–differential equations [11-15,22-24,30].

In this work, our aim is to solve a general form of boundary value problems for higher–order Volterra integro–differential equations by using the ADM and VIM.

3. Volterra Integro-differential Equation of Second Kind We consider the Volterra integro-differential equation of the second kind as follows:

$$\sum_{j=0}^{k} p_j(x)u^{(j)}(x) = f(x) + \int_a^x K(x,t)G(u(t))dt,$$

(4) We can rewrite Eq.(4) as follows:

$$p_j(x)u^{(j)}(x) = f(x) + \int_a^x K(x,t)G(u(t))dt,$$

$$\begin{split} & u^{(k)}(x) = \frac{f(x)}{p_k(x)} + \int_a^x \frac{K(x,t)G(u(t))}{p_k(t)} dt - \sum_{j=0}^{k-1} \frac{p_j(x)}{p_k(x)} u^{(j)}(x) \\ & u^{(k)}(x) = \frac{f(x)}{p_k(x)} + \int_a^x \frac{K(x,t)G(u(t))}{p_k(t)} dt - \sum_{j=0}^{k-1} \frac{p_j(x)}{p_k(x)} u^{(j)}(x) \end{split}$$

(5)

Let us set L^{-1} is the multiple integration operator as follows:

$$L^{-1}(.) := \int_{a}^{x} \int_{a}^{x} \dots \int_{a}^{x} \int_{a}^{x} (.) \underbrace{dtdt \dots dtdt}_{(6)}$$

k-times

From Eq.(5) and Eq.(6)

$$\begin{split} u(x) &= L^{-1}\{\frac{f(x)}{p_k(x)}\} + \sum_{r=0}^{k-1} \frac{(x-a)^r}{r!} \alpha_r + L^{-1}\{\int_a^x \frac{K(x,t)G(u(t))}{p_k(t)} dt\} \\ &- L^{-1}\{\sum_{j=0}^{k-1} \frac{p_j(x)}{p_k(x)} u^{(j)}(x)\}. \end{split}$$

(7)

We can obtain the term $\sum_{r=0}^{k-1} \frac{(x-a)^r}{r!} \alpha_r$ from the initial conditions. From

[8], we have

(8)
$$L^{-1}\left\{\int_{a}^{x} \frac{K(x,t)G(u(t))}{p_{k}(t)}dt\right\} = \int_{a}^{x} \frac{(x-t)^{k}K(x,t)G(u(t))}{(k!) p_{k}(t)}dt,$$

also

$$L^{-1}\left\{\sum_{j=0}^{k-1} \frac{p_j(x)}{p_k(x)} u^{(j)}(x)\right\} = \sum_{j=0}^{k-1} \int_a^x \frac{(x-t)^{k-1} p_j(t)}{(k-1)!} u^{(j)}(t) dt$$
(9)

By substituting Eq.(8) and Eq.(9) in Eq.(7) we obtain

$$u(x) = L^{-1}\left\{\frac{f(x)}{p_k(x)}\right\} + \sum_{r=0}^{k-1} \frac{(x-a)^r}{r!} \alpha_r + \int_a^x \frac{(x-t)^k K(x,t) G(u(t))}{(k!) p_k(t)} dt$$
$$- \sum_{j=0}^{k-1} \int_a^x \frac{(x-t)^{k-1} p_j(t)}{(k-1)! p_k(t)} u^{(j)}(t) dt.$$

(10)

We set,
$$L^{-1}\left\{\frac{f(x)}{p_k(x)}\right\} + \sum_{r=0}^{k-1} \frac{(x-a)^r}{r!} \alpha_r = F(x)$$

20

$$\frac{(x-t)^k K(x,t)}{(k!) p_k(t)} = K_1(x,t)$$
$$\frac{(x-t)^{k-1} p_j(x)}{(k-1)! p_k(x)} = K_2(x,t).$$

So, we have one-dimensional integro-differential equation as follows:

$$u(x) = F(x) + \int_{a}^{x} K_{1}(x,t)G(u(t))dt - \sum_{j=0}^{k-1} \int_{a}^{x} K_{2}(x,t)u^{(j)}(t)dt.$$

Description of the Methods

In this section, we present the semi–analytical techniques based on ADM and VIM to solve Volterra integro–differential equation:

3.1 Adomian Decomposition Method (ADM)

The ADM is applied to the following general nonlinear equation [1,30]:

$$Lu + Ru + Nu = f(x),$$
 (11)

where u is the unknown function, L is the highest-order derivative which is assumed to be easily invertible, R is a linear differential operator of order less than L and Nu represents the nonlinear terms and f is the source term. Applying the inverse operator L^{-1} to both sides of Eq.(11) and using the given conditions we obtain

$$u = F(x) - L^{-1}(Ru) - L^{-1}(Nu),$$
 (12)

where the function F(x) represents the terms arising from integrating the source term f(x). The nonlinear operator Nu = G(u) is decomposed as

$$G(u) = \sum_{n=0}^{\infty} A_n$$

(13)

where A_n ; n >0 are the Adomian polynomials determined formally as follows:

$$A_n = \frac{1}{n!} \left[\frac{d^n}{d\lambda^n} \left[G(\sum_{i=0}^{\infty} \lambda^i u_i) \right] \right]_{\lambda=0}$$

The Adomian polynomials were introduced in [30] as:

$$A_0 = G(u_0); \quad A_1 = u_1 G'(u_0); \quad A_2 = u_2 G'(u_0) + \frac{1}{2} u_1^2 G''(u_0)$$

$$A_3 = u_3 G'(u_0) + u_1 u_2 G''(u_0) + \frac{1}{3} u_1^3 G'''(u_0), \dots$$

The standard decomposition technique represents the solution of u in Eq.(11) as the following series:

$$u = \sum_{n=0}^{\infty} u_n$$
(14)

The nonlinear terms G(u(t)) $D^{j}(u(x)), (D^{j} = \frac{\partial^{j}}{\partial x^{j}}$ and is derivative operator), are usually represented by an infinite series of the so called Adomian polynomials as follows:

$$G(u(t)) = \sum_{i=0}^{\infty} \sum_{i=0}^{\infty} A_i, D^{i}(u(x)) = \sum_{i=0}^{\infty} B_{ij}, \sum_{i=0}^{\infty} B_{ij},$$

where A_i and B_{ij} ($i \ge 0, j = 0, 1, ..., k - 1$) are the Adomian polynomials. where, the components $u_0, u_1, ...$ are usually determined recursively by

$$u_0 = F(x),$$
 (15)
 $un+1 = -L^{-1}(Run) - L^{-1}(An).$

Substituting (12) into (15) leads to the determination of the components of u. Having determined the components $u_1, u_2, ..., the solution u in a series form defined by Eq.(14).$

Now, we apply ADM to find the approximate solutions of Eq.(11), we can write the iterative formula as follows:

$$u_{0}(x) = F(x),$$
(16)
$$u_{n+1}(x) = \int_{a}^{x} k_{1}(x,t)A_{n}dt - \sum_{j=0}^{K-1} \int_{a}^{x} k_{1}(x,t)A_{n}dt$$

$$\int_{a}^{x}k_{1}\left(x,t\right) A_{n}dt-$$

$$\sum_{j=0}^{K-1} \int_a^x k_1(x,t) A_n dt$$

Convergence aspects of the ADM have been investigated in [19]. For later numerical computation, let the expression

$$Y_n(x) = \sum_{k=0}^{n-1} u_k \sum_{k=0}^{n-1} u_k$$

denote the n-term approximation to u(x).

3.2 Variational Iteration Method (VIM)

This method has been applied to solve a large class of linear and nonlinear problems with approximations converging rapidly to exact solutions.

The main idea of this method is to construct a correction functional form using general Lagrange multipliers. These multipliers should be chosen such that its correction solution is superior to its initial approximation, called trial function. It is the best within the flexibility of trial functions. Accordingly, Lagrange multipliers can be identified by the variational theory [29,30]. A complete review of VIM is available in [7,16].

The initial approximation can be freely chosen with possible unknowns, which can be determined by imposing boundary/initial conditions. To illustrate, we consider the following general differential equation:

$$Lu(t) + Nu(t) = f(t),$$

(17)

where L is a linear operator, N is a nonlinear operator and f(t) is inhomogeneous term. According to variational iteration method [5,24], the terms of a sequence u_n are constructed such that this sequence converges to the exact solution. The terms u_n are calculated by a correction functional as follows:

$$u_{n+1}(t) = u_n(t) + \int_0^t \lambda(\tau) (Lu_n(\tau) + N\tilde{u}(\tau) - f(\tau)) d\tau.$$
(18)

The successive approximation $u_n(t), n \ge 0$ of the solution u(t) will be readily obtained upon using the obtained Lagrange multiplier and by using any selective function u_0 .

The zeroth approximation u_0 may be selected using any function that just satisfies at least the initial and boundary conditions with λ determined, sev-

eral approximations $u_{_{n}}(t),n\geq 0$ follow immediately. Consequently, the exact solution may be obtained by using

$$u(t) u(t) = \lim_{n \to \infty} u(t)$$
 (19)

4. Numerical Results

In this section, we present the numerical techniques based on ADM and VIM to solve Volterra integro-differential equations:

Example 1.

Consider the Volterra integro-differential equation as follow:

$$u^{(4)}(x) - u(x) = x(1 + e^x) + 3e^x - \int_0^x u(t)dt, \quad 0 < x < 1$$

with the boundary conditions:

$$u(0) = 1, u(1) = 1 + e, u''(0) = 2, u''(1) = 3e.$$
 (21)

The exact solution is $u(x) = 1 + xe^{x}$.

The recursive of ADM

$$u_0 = 1 + Ax + x^2 + \frac{1}{3!}Bx^3 + L^{-1}(x + xe^x + 3e^x)$$
$$u_{n+1} = L^{-1}\{u_n(x)\} - L^{-1}\{\int_a^x A_n(t)dt\}, \ n \ge 0.$$

Using the recursive algorithm,

$$\begin{split} & \mathcal{T}_{2}(x) = (f_{0} + \frac{1}{360}x^{6}) + (f_{1} - \frac{1}{1209600}x^{10} - \frac{1}{19958400}x^{11}) \\ & \mathcal{T}_{3}(x) = (f_{0} + \frac{1}{144}x^{6} + \frac{1}{1680}x^{7}) + (f_{1} - \frac{1}{19958400}x^{11} - \frac{1}{159667200}x^{12}) \\ & \mathcal{T}_{4}(x) = (f_{0} + \frac{1}{144}x^{6} + \frac{1}{840}x^{7} + \frac{1}{10080}x^{8}) + (f_{1} + \frac{1}{39916800}x^{11} - \frac{1}{239500800}x^{12} - \frac{1}{1556755200}x^{13}) \end{split}$$

,

24

where

$$\begin{split} f_0 &= 1 + Ax + x^2 + \frac{1}{3!}Bx^3 + \frac{1}{8}x^4 + \frac{1}{4!}x^5, \\ f_1 &= \frac{1}{4!}x^4 + \frac{A-1}{120}x^5 + \frac{2-A}{720}x^6 + \frac{B-2}{5040}x^7 + \frac{3-B}{40320}x^8 + \frac{1}{181440}x^9 \end{split}$$

where the constants A = u'(0) and B = u''(0) can be determined by imposing the boundary condition (21) in $u_1(x)$, then we have

A =
$$0.9740953834$$
, B = 3.1897820557 for Y_2
A = 0.9944789128 , B = 3.0382130987 for Y_3

A = 0.9989095252, B = 3.0073098797 for Y_{A}

The rest of components of the iteration formulas can be obtained in the same manner.

Using VIM, the iterative formula can be written in the following form:

$$u_{n+1}(x)$$
(23)
= $u_n(x) + \int_0^x (\frac{1}{3!}s^3 - \frac{x}{2!}s^2 + \frac{x^2}{2!}s - \frac{1}{3!}x^3)[u_n^{(4)}(s) - u_n(s) - s(1+e^s) - 3e^s + \int_0^s u_n(t)dt]ds$

Now, starting with the initial solution

$$\begin{aligned} u_0(x) &= 1 + Ax + \frac{1}{2}x^2 + \frac{1}{3!}Bx^3, \\ u_1(x) &= 1 + Ax + x^2 + \frac{1}{3!}Bx^3 + 0.042(24 + 8.882(10^{-16})e^x(-1+x)(2.702(10^{16} + x(3+x)))) \\ &+ x^2(-12 + x(-8 + x(1 + A(0.2 - 0.3)x + x2(0.07 + x(-0.01 + 0.005B - 0.0006Bx)))))) \end{aligned}$$

where the constants A = u'(0) and B = u'''(0) can be determined by imposing the boundary condition (21) in $u_1(x)$, then we have

 $\mathsf{A} = 0.9991323308076788,$

 $\mathsf{B} = 3.005849664438371.$

The rest of components of the iteration formulas can be obtained in the same manner.Conclusion

We discussed the ADM and VIM to solve boundary value problems for higherorder integro-differential equations. The results obtained with the minimum amount of computation are compared with the exact solutions to show the efficiency of the techniques. The results show that the variational iteration

method is of high accuracy, more convenient and efficient for solving integro-differential equations.

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